

SM-HYD SERIES | LVDT

Designed for integration into hydraulic and pneumatic cylinders or servo valves.

- Screw flange M18x1,5 / M30x1,5 or plug-in flange Ø18
- Pressure up to 400 bar
- Sensor working temperature up to 150°C
- Linearity up to ±0.10 %
- Measurement range 2...180 mm





The SM-HYD-series are used in hydraulic cylinders with a maximum pressure resistance of up to 400 bar. The sensors are especially suited to be installed in harsh industrial environments where a high electromagnetic tolerance is required. The sensor works nearly unaffected by electric or magnetic fields.

This sensor enables a connection between the hydraulic cylinder and the machine control.



TECHNICAL DATA - SENSORS

SENSOR		
Ranges [mm]	2180 mm (see chart on page 3)	
Linearity [% of FS]	±0.20 % - 0.80 % (see chart on page 3), 0.10 % for selected models	
Temperature range	-40+120 °C, optional up to 150 °C (H-option)	
Vibration stability DIN IEC68T2-6	10 G	
Shock stability DIN IEC68T2-27	200 G / 2 ms	
Connection	4 core cable or M12-connector with coupling nut	
cable TPE (standard)	ø 4.5 mm, 0.14 mm², non-halogen, suitable for drag chains	
PTFE (option H)	ø 4.8 mm, 0.24 mm², max. temperature 200 °C, UL-Style 2895	
Max. cable length	100 m between sensor and electronics	

TECHNICAL DATA - ELECTRONICS

ELECTRONICS	IMCA EXTERNAL ELECTRONICS*	KAB CABLE ELECTRONICS	
Output signal	420 mA (load < 300 Ohm) $05 \text{ V}, \pm 5 \text{ V (load } > 5 \text{ kOhm)}$ $010 \text{ V}, \pm 10 \text{ V (load } > 10 \text{ kOhm)}$		
Temperature coefficient	-0.0055, ±0.002 %/K		
Resolution**	0.04% of FS		
Corner frequency	300 Hz/-3 dB (6-pole Bessel)		
Isolation stability	> 1000 VDC		
Power supply	936 VDC		
Current consumption	75 mA at 24 VDC 65 mA at 24 VDC		
	150 mA at 12 VDC	140 mA at 12 VDC	
Sensor supply	3 V _{eff} , 3 kHz (adjustable, 1-18 kHz)		
Working temperature	-40+85 °C		
Storage temperature	-40+85 °C		
Housing	polyamide PA6.6, meets UL94-VO	ABS	
Mounting	on DIN EN-rail	bore diameter ø 5,5	

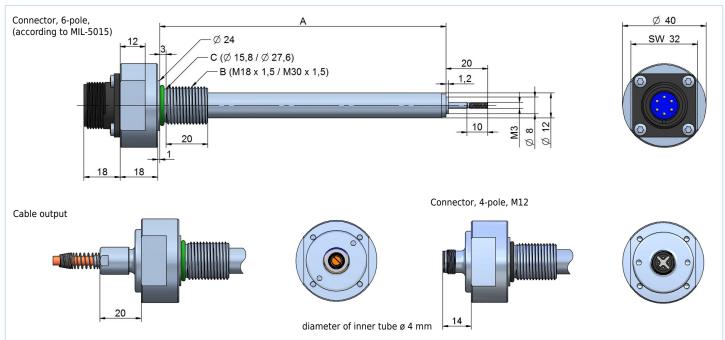
^{** 98.5%} confidence interval (confidence limit)

TECHNICAL DIMENSIONS

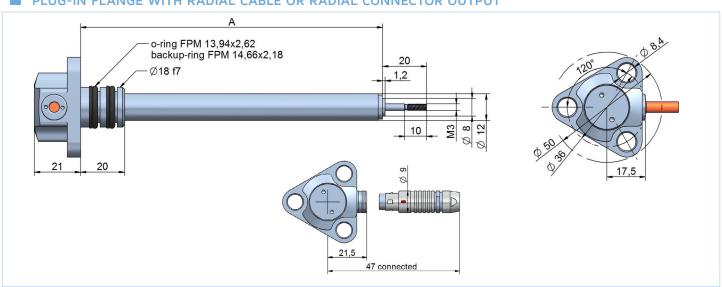
RANGE (FS) [MM]	ТҮРЕ	BODY TYPE	BODY LENGTH A [MM]	LINEARITY [%] (STANDARD)	LINEARITY [%] (OPTIONAL)
02	SM2-HYD	1	48	0.30	0.20
05	SM5-HYD	1	54	0.30	0.20
010	SM10-HYD	1	64	0.30	0.20
025	SM25-HYD	2	94	0.30	0.20
025	SM25-HYD	1	137	0.30	0.20
050	SM50-HYD	2	144	0.30	0.20
050	SM50-HYD	1	207	0.30	0.20
0100	SM100-HYD	2	220	0.80	-
0100	SM100-HYD	1	244	0.30	0.20
0120	SM120-HYD	1	227	0.80	-
0140	SM140-HYD	1	260	0.80	-
0160	SM160-HYD	1	336	0.80	-
0180	SM180-HYD	1	300	0.80	-

other ranges on request

DIFFERENT OUTPUT TYPES WITH FLANGE TYPE THREAD M18 X 1,5 / M30 X 1,5

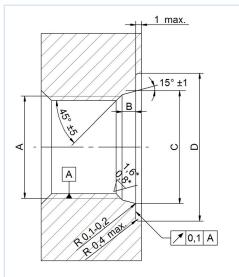


PLUG-IN FLANGE WITH RADIAL CABLE OR RADIAL CONNECTOR OUTPUT



INSTALLATION DRAWING

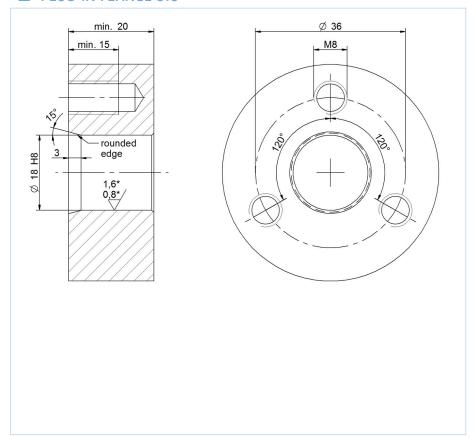
SCREW FLANGE M18 / M30



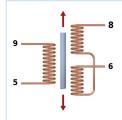
* note: Rz = 1,6 for non pulsating pressure Rz = 0,8 for pulsating pressure

	M18X1,5	M30X1,5
Α	M18x1,5	M30x1,5
В	2,4	3,1
С	19,8	32,4
D	26	42

■ PLUG-IN FLANGE S18



AC-OUTPUT



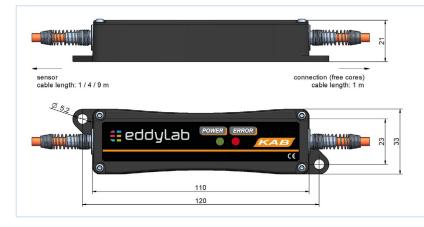
assignment for TPE-cable:

white (5): primary 2 black (6): secondary 2 brown (9): primary 1 blue (8): secondary 1

assignment for PTFE-cable:

white (5): primary 2 green (6): secondary 2 yellow (9): primary 1 brown (8): secondary 1

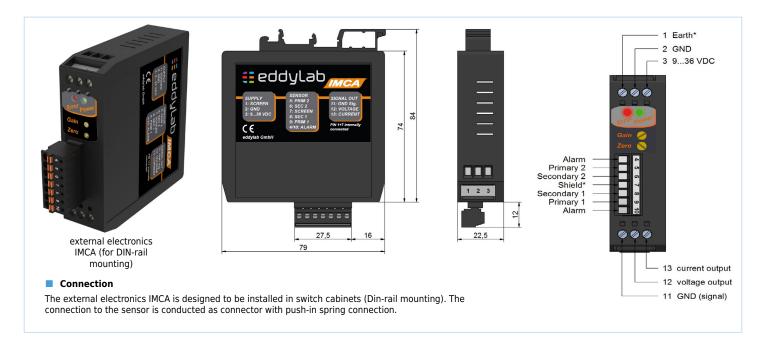
CABLE ELECTRONICS KAB



FUNCTION	CABLE TPE	CABLE PTFE-UL
V+	brown	yellow
GND	blue	brown
signal	white	white
signal GND	black	green

If not specified otherwise the cable electronics is placed at 1 m from the end of the cable.

EXTERNAL ELECTRONICS IMCA

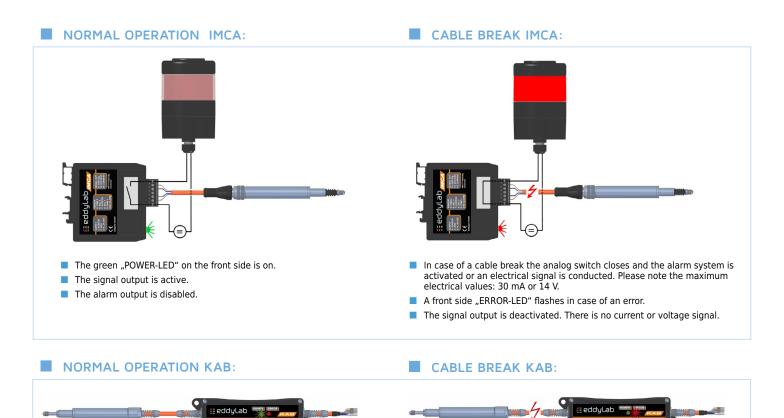


CABLE BREAK DETECTION

■ The green "POWER-LED" on the front side is on.

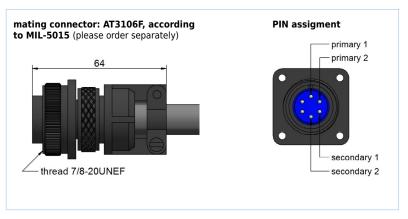
The electronics by eddylab feature a built-in cable break detection. This is achieved by an impedance measurement of the LVDT's secondary coil. If the sensor cable is cut, the impedance on the secondary connections of the electronics change regardless of the push rod position, triggering the cable break detection. This feature is based on a broken secondary connection. A partial cable break of the primary connections (cables between primary coil and electronics) will not activate this function. The electronics vary in their functional range. The external electronics IMCA offers the widest range. The cable electronics KAB only visualises a cable break by a red LED.

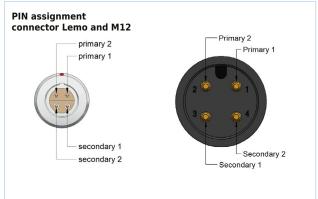
IMCA: For the use of the cable break functions an alarm system (signal lamp, acoustic alarm device) or an alarm input of the PLC must be connected to the 7-pole terminal. The circuit board features a analog switch which is a normally open.



A front side "ERROR-LED" flashes in case of an error.

ELECTRICAL CONNECTION





ACCESSORIES

CONNECTION CABLE (SHIELDED) FOR CONNECTOR OUTPUT M12

CABLE M12 ANGULAR CONNECTOR		
K4P2M-SW-M12 2 m		
K4P5M-SW-M12	5 m	
K4P10M-SW-M12	10 m	

CABLE M12 WITH STRAIGHT CONNECTOR		
K4P2M-S-M12 2 m		
K4P5M-S-M12	5 m	
K4P10M-S-M12 10 m		



MATING CONNECTOR FOR SELF ASSEMBLY (SHIELDED)

	STRAIGHT CONNECTOR D4-G-M12-S M18 / M30 FLANGE	ANGULAR CONNECTOR D4-W-M12-S M18 / M30 FLANGE	STRAIGHT CONNECTOR LEMO-FGG.0T S18 FLANGE
Protection class	IP67		IP68
Temperatur	-25+90 °C		-40150 °C
Mode of connection	spring clos	soldering contact	
Cable diameter	ø 48 mm		Ø 4,55,0 mm
Conductor	0,140,34 mm²		0,140,25 mm ²



ADJUSTMENT OF ZERO POINT AND GAIN

Each sensor, manufacted by eddylab, is basically adjusted and calibrated. You will receive a traceable calibrated measurement equipment, adjusted and tested in the company's own high-end calibration laboratory, and a calibration certificate. Please note: If the zero point or gain is changed the calibration certificate will lose validity. The potentiometers shall be protected by a label against unauthorised access. In some cases, it is necessary to adjust the zero point and gain, e.g. with hydraulic cylinders or reduced measurement ranges. In this case, the output signal can be adapted to the mechanical stroke of the measurement object precisely. Please note that the zero point and gain may shift for long cable length between sensor and electronics. Thus install the sensor with the according cable length to the electronics and then adjust zero point and gain.

- Push rod entirely in adjust offset. Move the sensor to the zero point of the measuring range and set the offset potentiometer on 4 mA/0 V for the output signal
- Push rod entirely out adjust gain. Move the sensor to the end of the measuring range (push rod moved out) and set the gain potentiometer on 20 mA /10 V/5 V for the output signal.

Running direction of signal: If the push rod is moving into the sensor (e.g. sprung load pushed in), the signal is reducing. If the push rod is moving out, the output signal is increasing. The running direction of the signal can also be inverted.

ORDER CODE SENSOR

X - HYD - X - X - X X X0 0 0 0 **(b)**

a measurement ranges [mm]

2/5/10/25/50/100 120 / 140 / 160 / 180

b type of flange

18 = thread M18 x 1,5thread M30 x 1,5 plug-in flange ø18

G output

connector output (MIL-5015 / LEMO)

M12 =connector output (M12)

cable output

d cable / connector output

S1: sensor with connector output

1 = connector output

S2: sensor with cable output, open cable end (for IMCA)

= TPE cable 2 m

TPE cable 5 m

С TPE cable 10 m

D PTFE-UL cable 2 m (option H)

Ε PTFE-UL cable 5 m (option H)

PTFE-UL cable 10 m (option H)

S3: sensor with cable output for KAB

G = TPE cable 2 m

Н TPE cable 5 m

Τ TPE cable 10 m

b KAB: type of cable / length

E1: for sensor with cable output

PTFE-UL cable 2 m (option H)

PTFE-UL cable 5 m (option H)

PTFE-UL cable 10 m (option H)

e linearity

0,30 / 0,80 % (see table page 3) 1 =

2 0,20 % =

3 0.10 %

f temperature range

= -40...+120 °C (standard) 1

-40...+150 °C (option H)

g housing

1 = standard body length

short body length

ORDER CODE ELECTRONICS

IMCA - 24V -

KAB - 24V - X - X

type

IMCA external electronics KAR cable electronics

a output signal

020A 0...20 mA

420A 4...20 mA

10V 0...10 V

5V 0...5 V

±5V

±10V -10...10 V

-5...5 V

A = cable 2 m, M12 straight female conn. cable 2 m, M12 angular female conn. C = cable 5 m, M12 straight female conn.

= KAB integrated in sensor cable

E2: for sensor with connector output

D cable 5 m, M12 angular female conn.

E = cable 10 m, M12 straight female conn.

cable 10 m, M12 angular female conn.

b KAB: type of cable / length

E3: for sensor with cable output

= KAB integrated in sensor cable, M12 connector

E4: for sensor with connector output

M12A = cable 2 m, M12 straight female conn., M12 conn.

M12B = cable 2 m, M12 angular female conn., M12 conn.

M12C = cable 5 m, M12 straight female conn., M12 conn.

M12D = cable 5 m, M12 angular female conn., M12 conn.

M12E = cable 10 m, M12 straight female conn., M12 conn.

M12F = cable 10 m, M12 angular female conn., M12 conn.

possible combinations:

- S3+E1: sensor with cable output, KAB integrated in sensor cable
- S3+E3: sensor with cable output, KAB integrated in sensor cable, M12 connector
- S1+E2: sensor with connector output, cable electronics with cable K4PxM
- S1+E4: sensor with connector output, cable electronics with cable K4PxM, M12 connector
- IMCA: sensor with connector output (S1), cable K4PxM, external electronics IMCA
- IMCA: sensor with cable output (S2), external electronics IMCA

